

*Phenix User Workshop, Pittsburgh Diffraction Conference,
October 14th 2023*



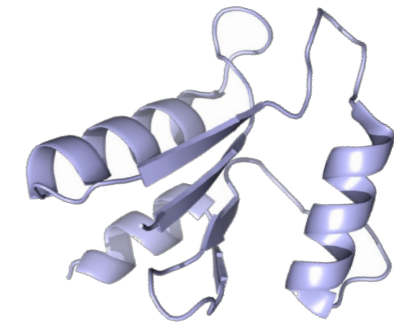
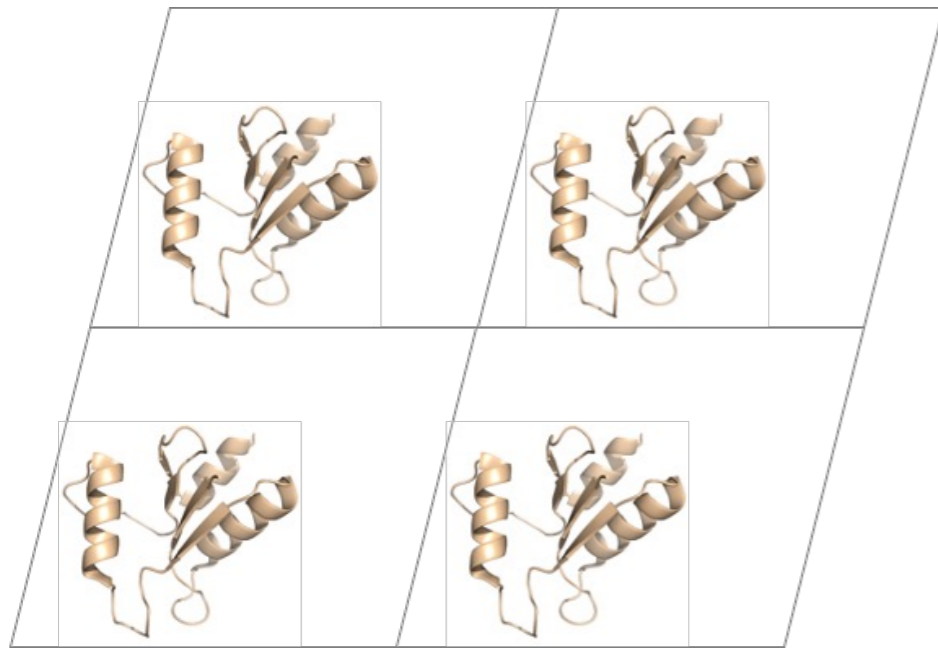
Molecular Replacement

Dorothee Liebschner
Lawrence Berkeley Laboratory

Molecular Replacement (MR)

MR = Use a known molecular model to solve the unknown crystal structure of a related molecule.

Crystal of unknown structure

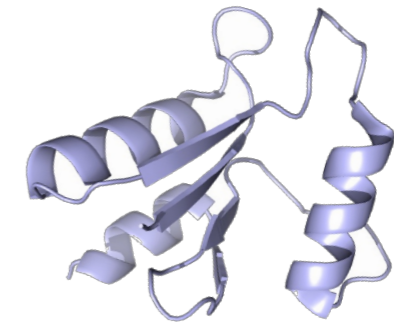
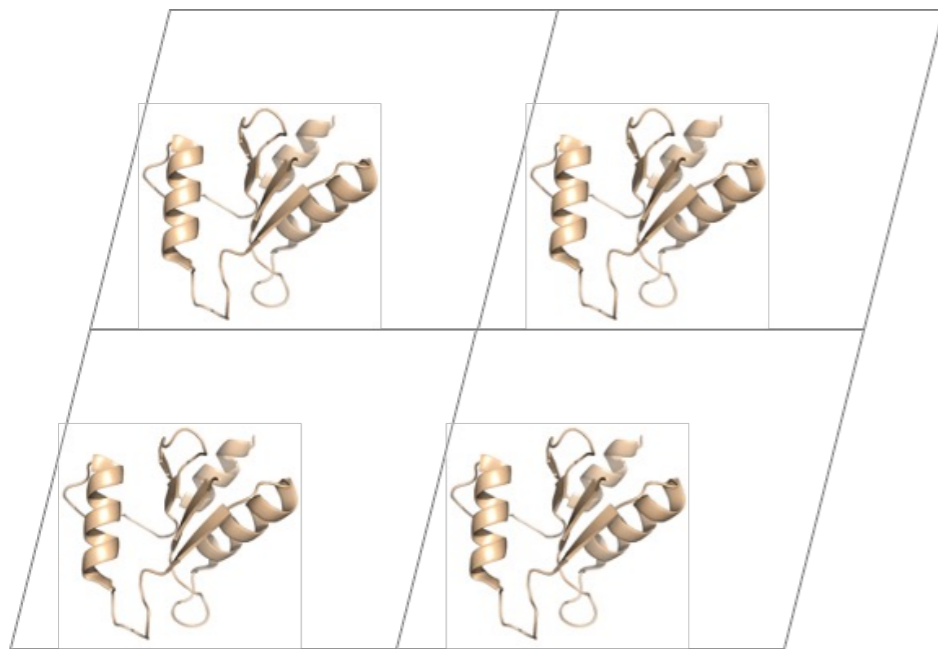


Known model

Molecular Replacement (MR)

MR = Use a known molecular model to solve the unknown crystal structure of a related molecule.

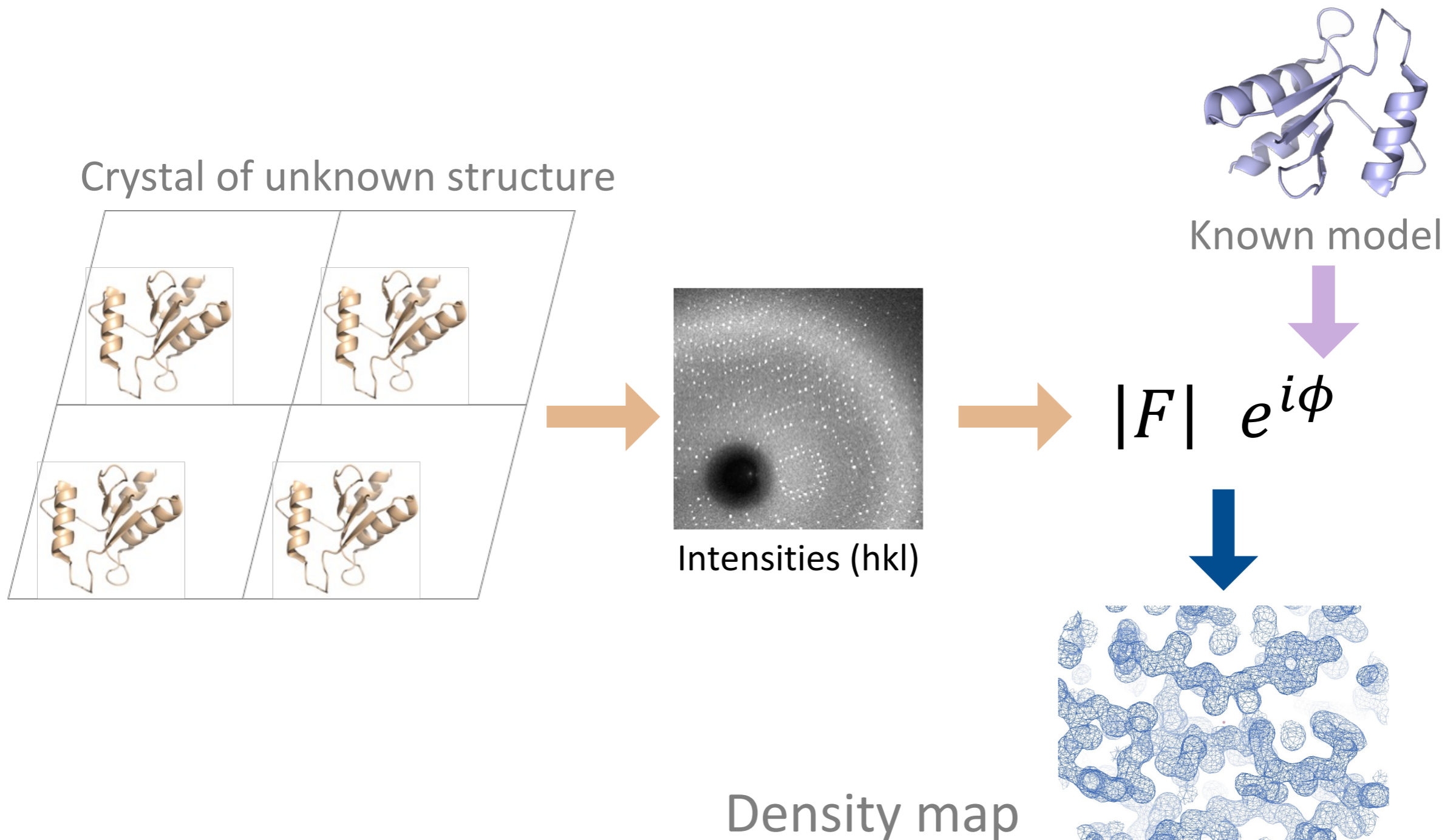
Crystal of unknown structure



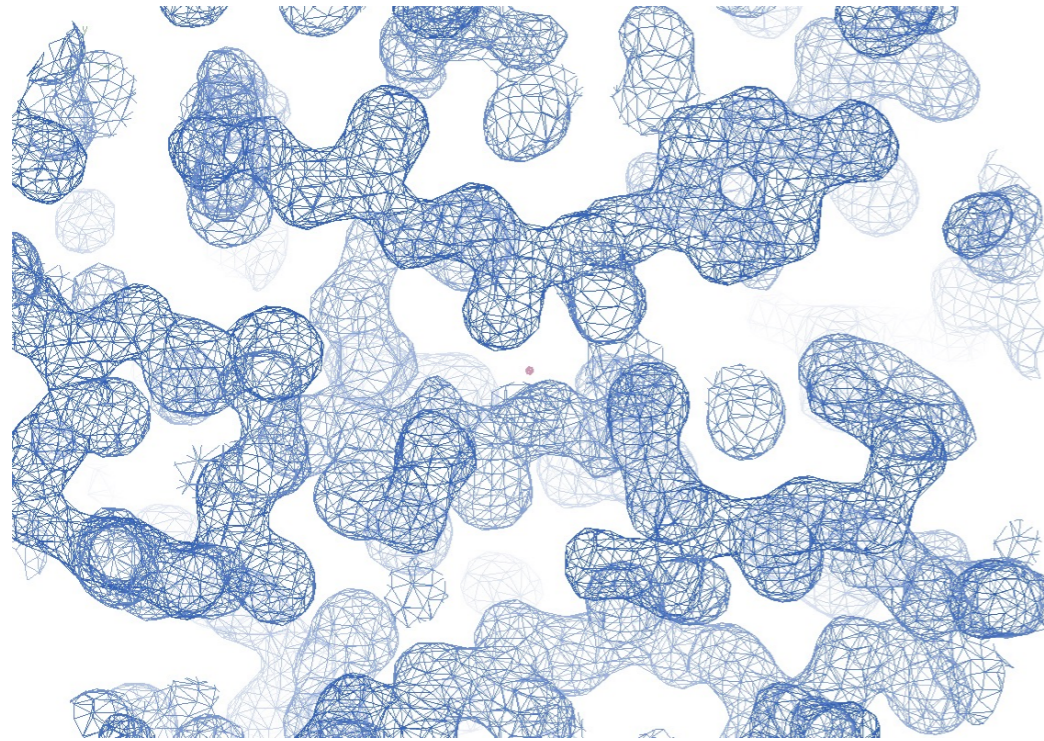
Known model

Known model provides initial estimates of the phases of the unknown structure.

Molecular Replacement (MR)

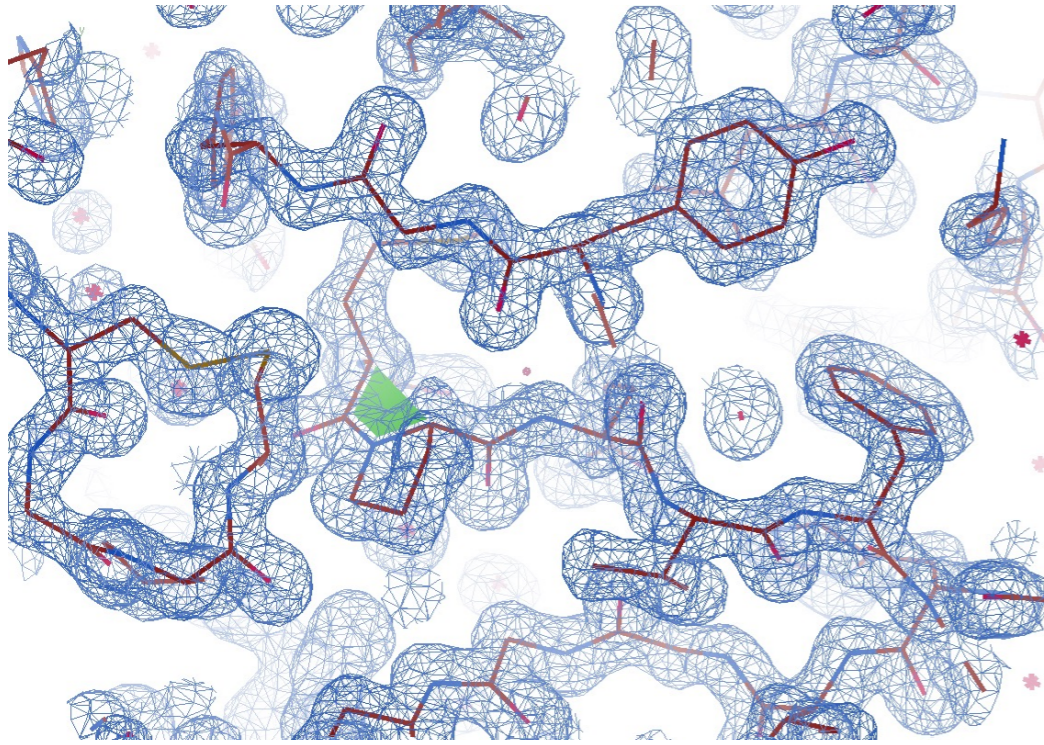


Molecular Replacement (MR)



If we know the density...

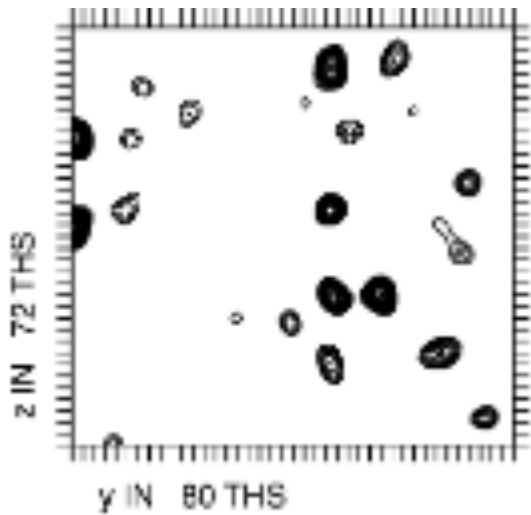
Molecular Replacement (MR)



If we know the density...

... then we can
determine the structure

How to recover phases



Experimentally

Exploit the properties of a few special atoms:

- Anomalous scattering
- A large number of electrons

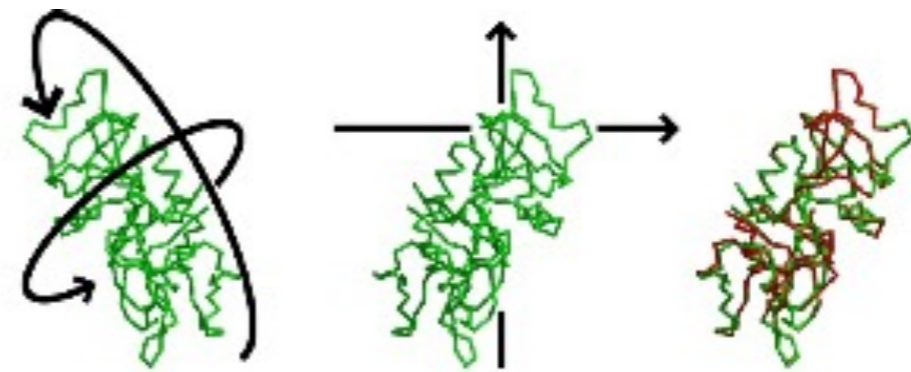
Computationally

- *Molecular Replacement (MR)*

A previously known structure provides initial phase estimates for a new structure

- *Direct Methods*

Phase relationships can be formulated by assuming the positivity and atomicity of the electron density



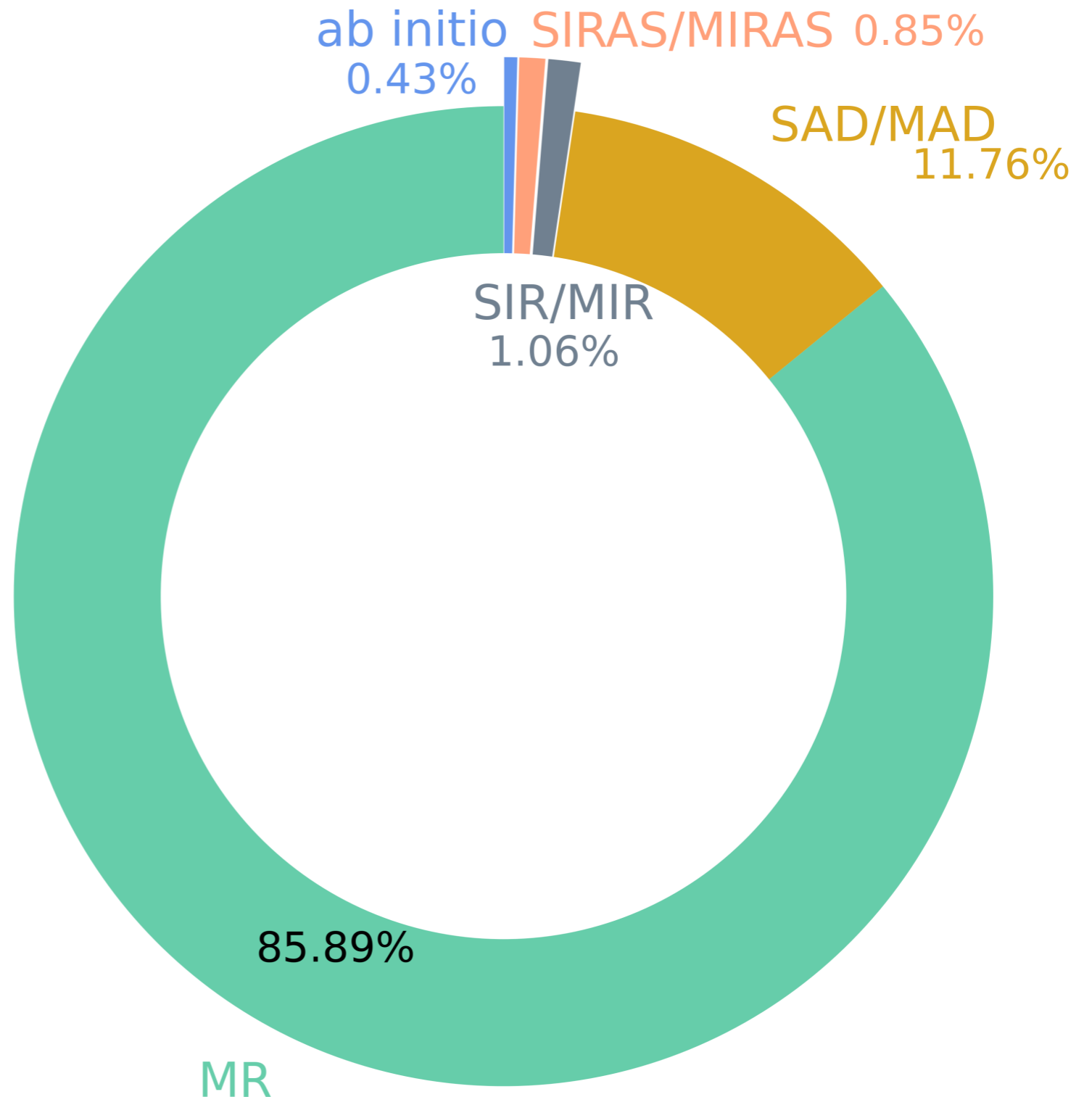
Phasing methods in the PDB

MR method:

- Fast
- Cheap
- Highly automated

Known structure:

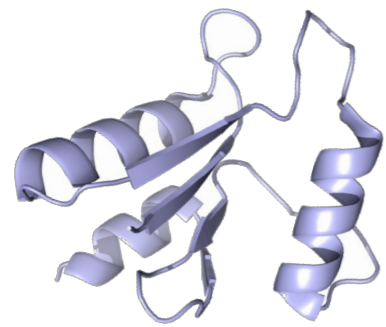
- Number of known structures increases (PDB)
- Predicted models



Note: Not all models in the PDB have (correct) info.

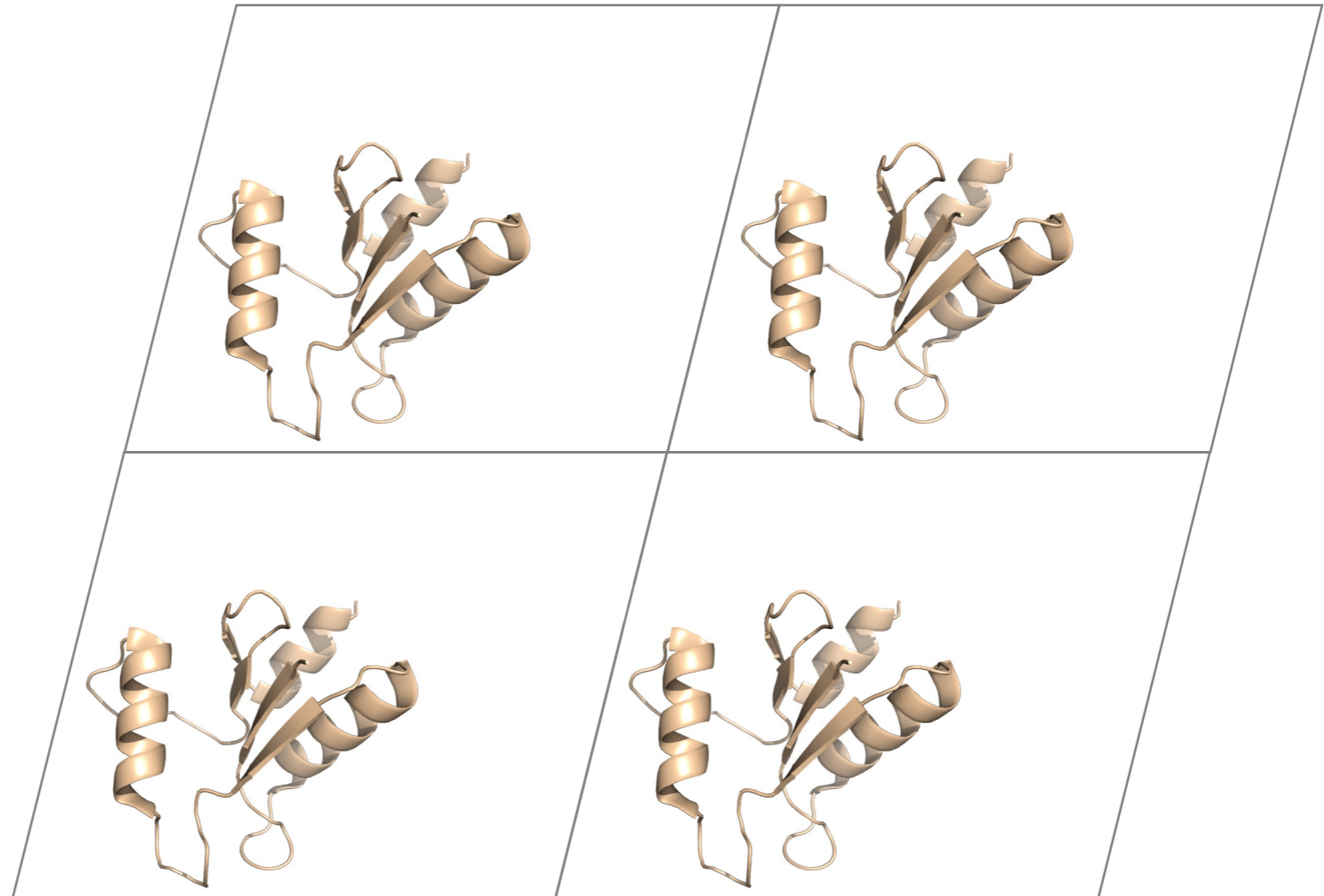
Molecular replacement: Approach

Try to match the known model with the unknown structure.



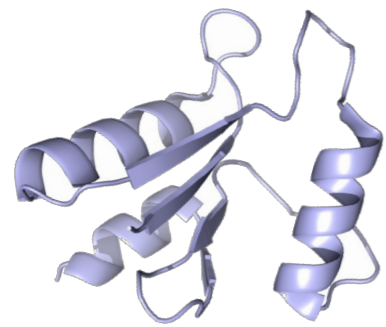
Search Model

Crystal of unknown structure



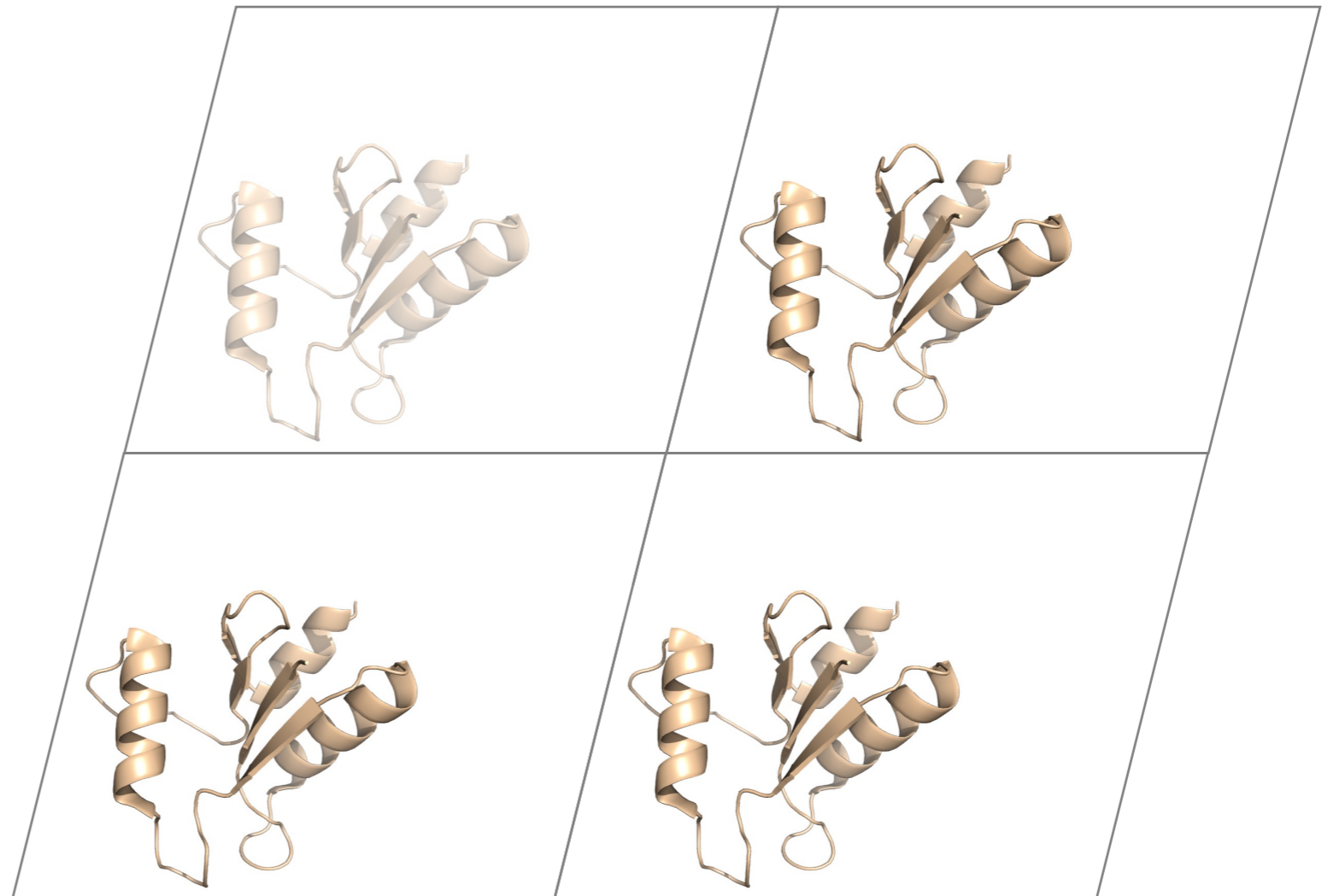
Molecular replacement: Approach

- Try all possible positions and orientations of the model
- Find where the predicted diffraction best matches the observed diffraction.



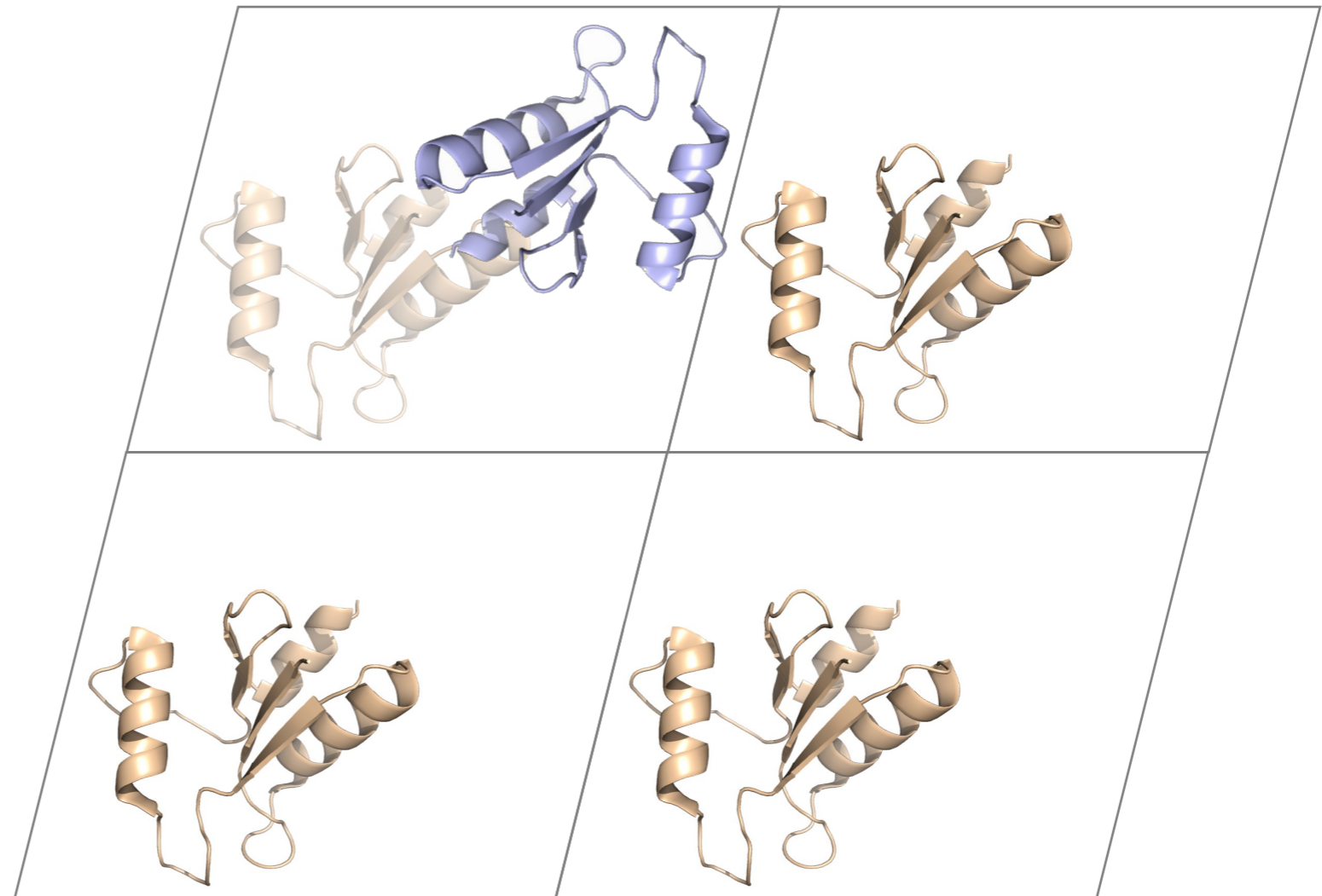
Search Model

Crystal of unknown structure

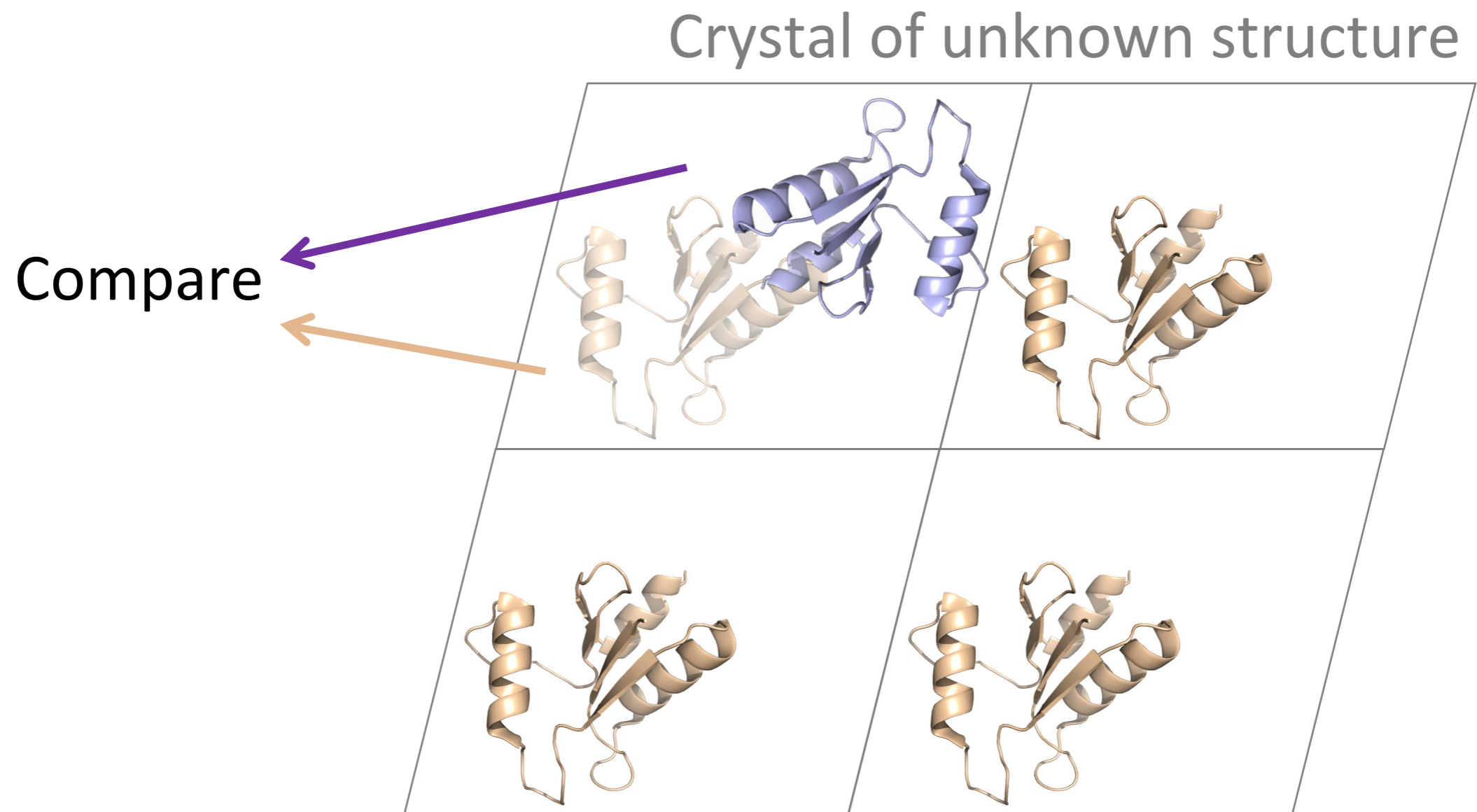


Molecular replacement: Approach

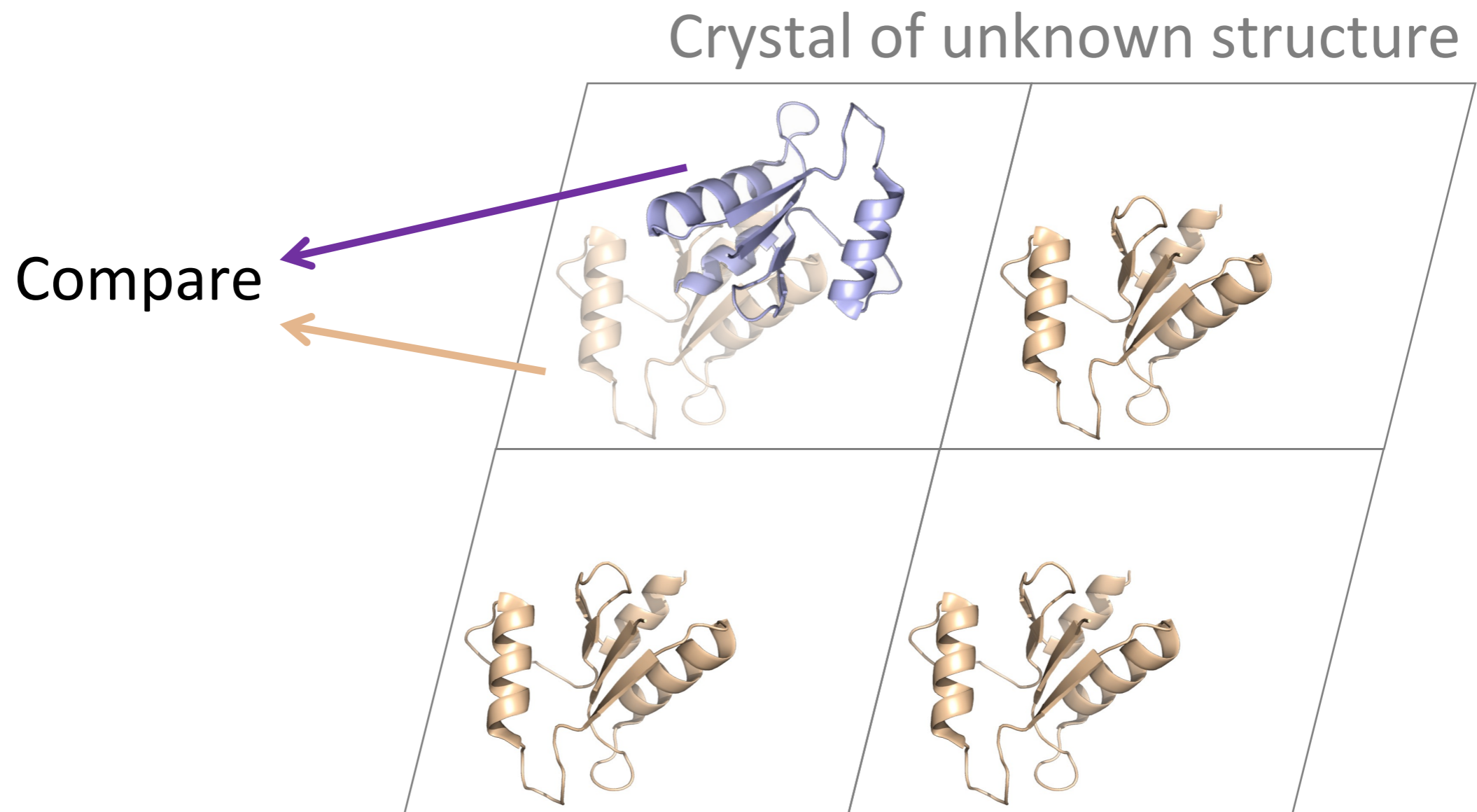
Crystal of unknown structure



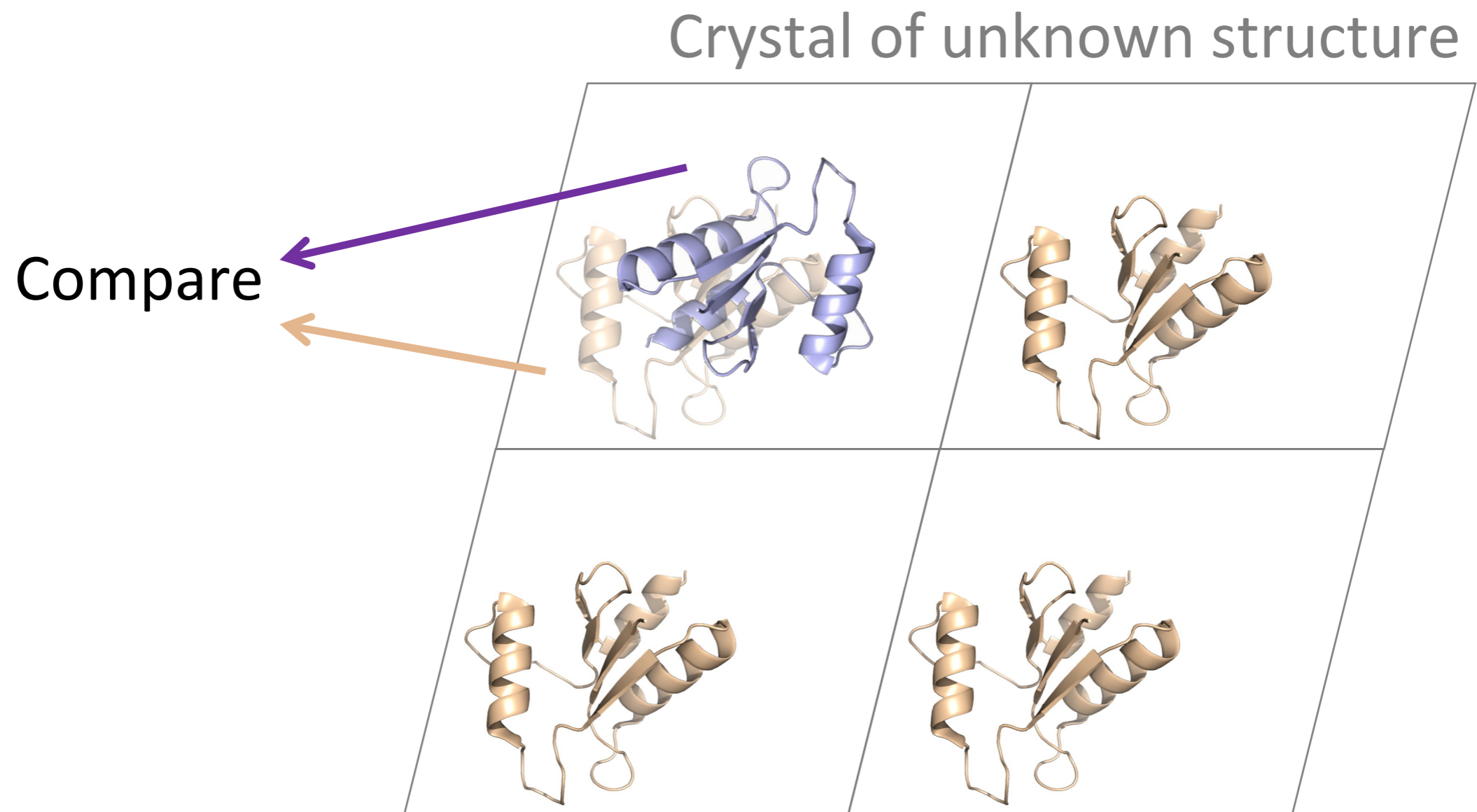
Molecular replacement: Approach



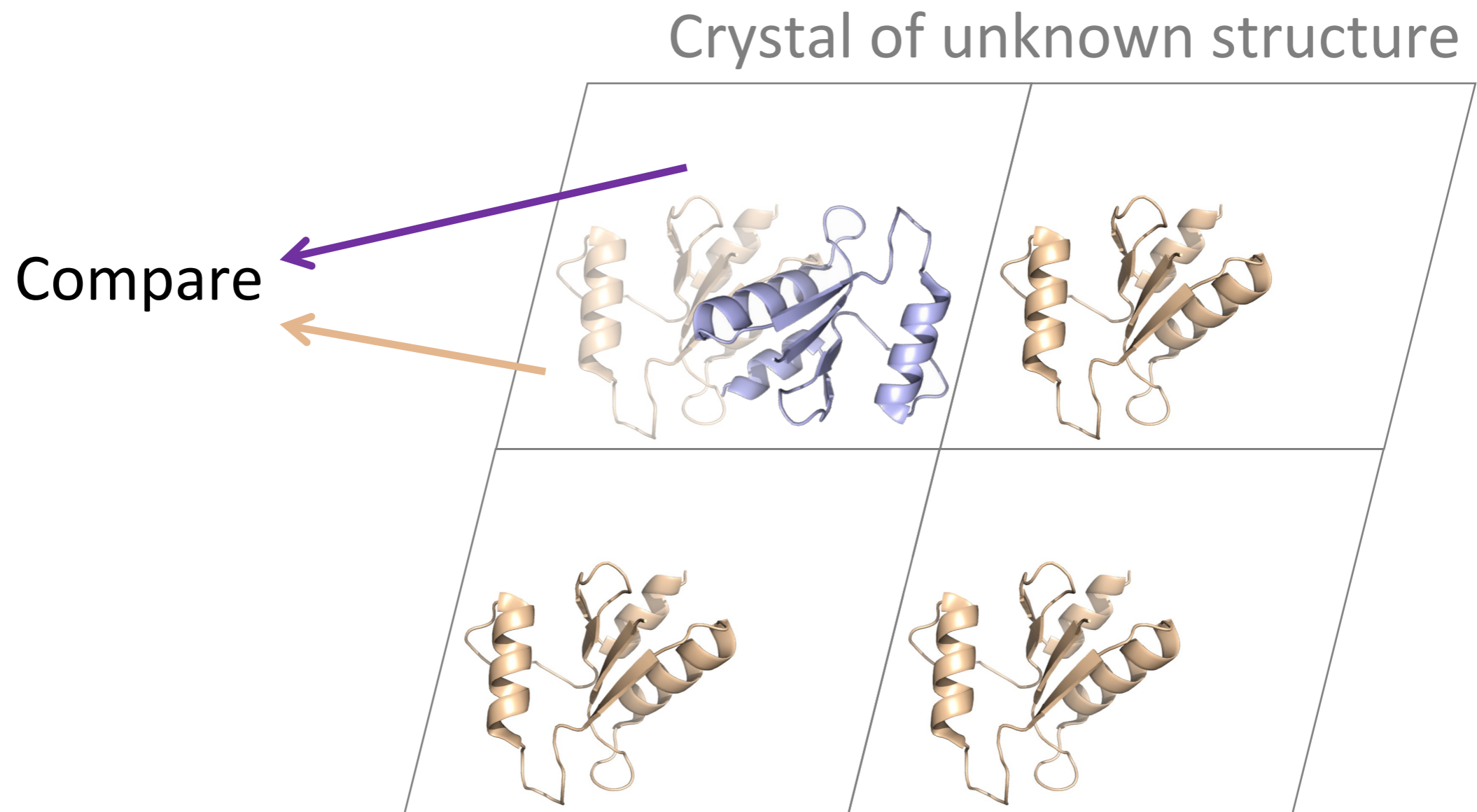
Molecular replacement: Approach



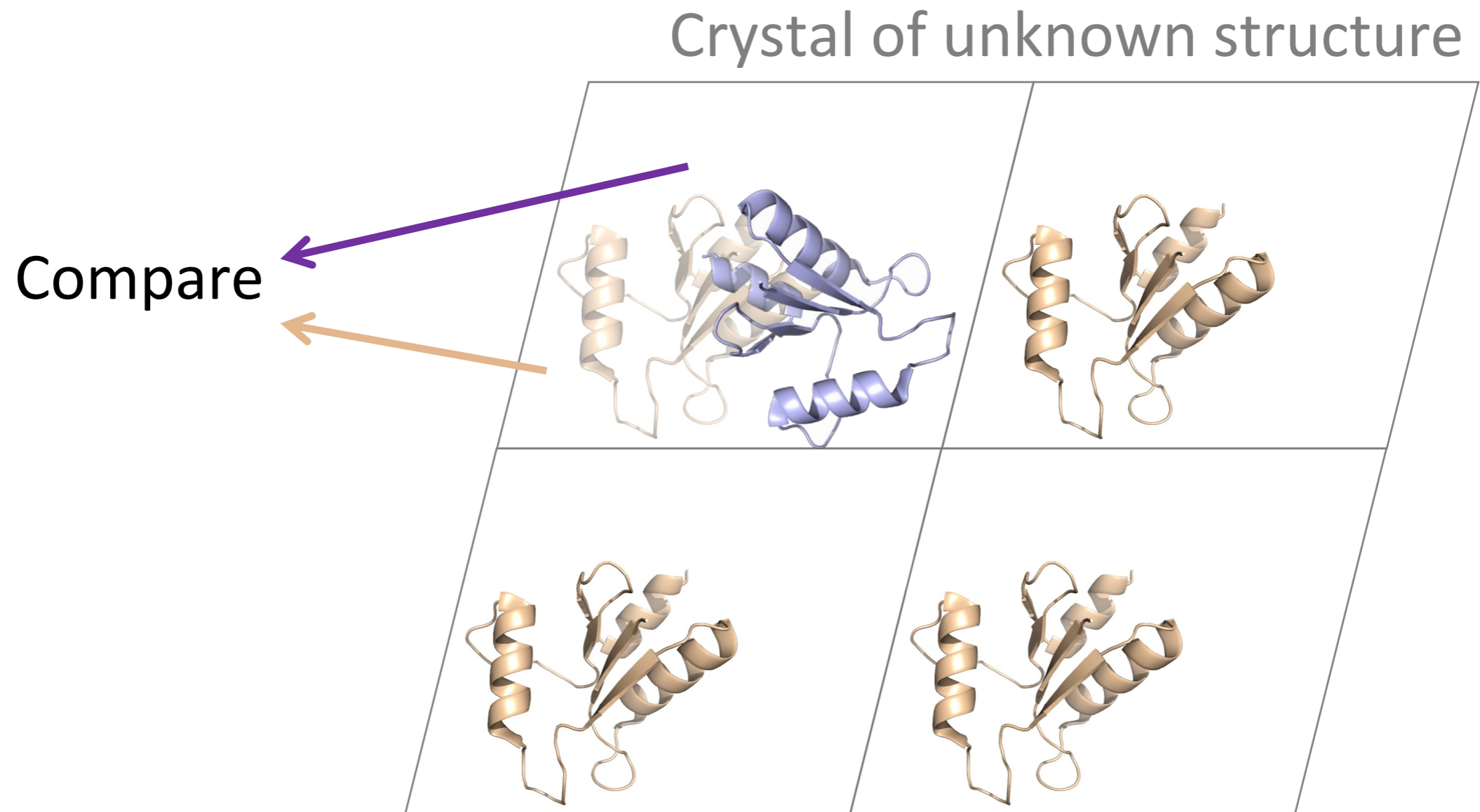
Molecular replacement: Approach



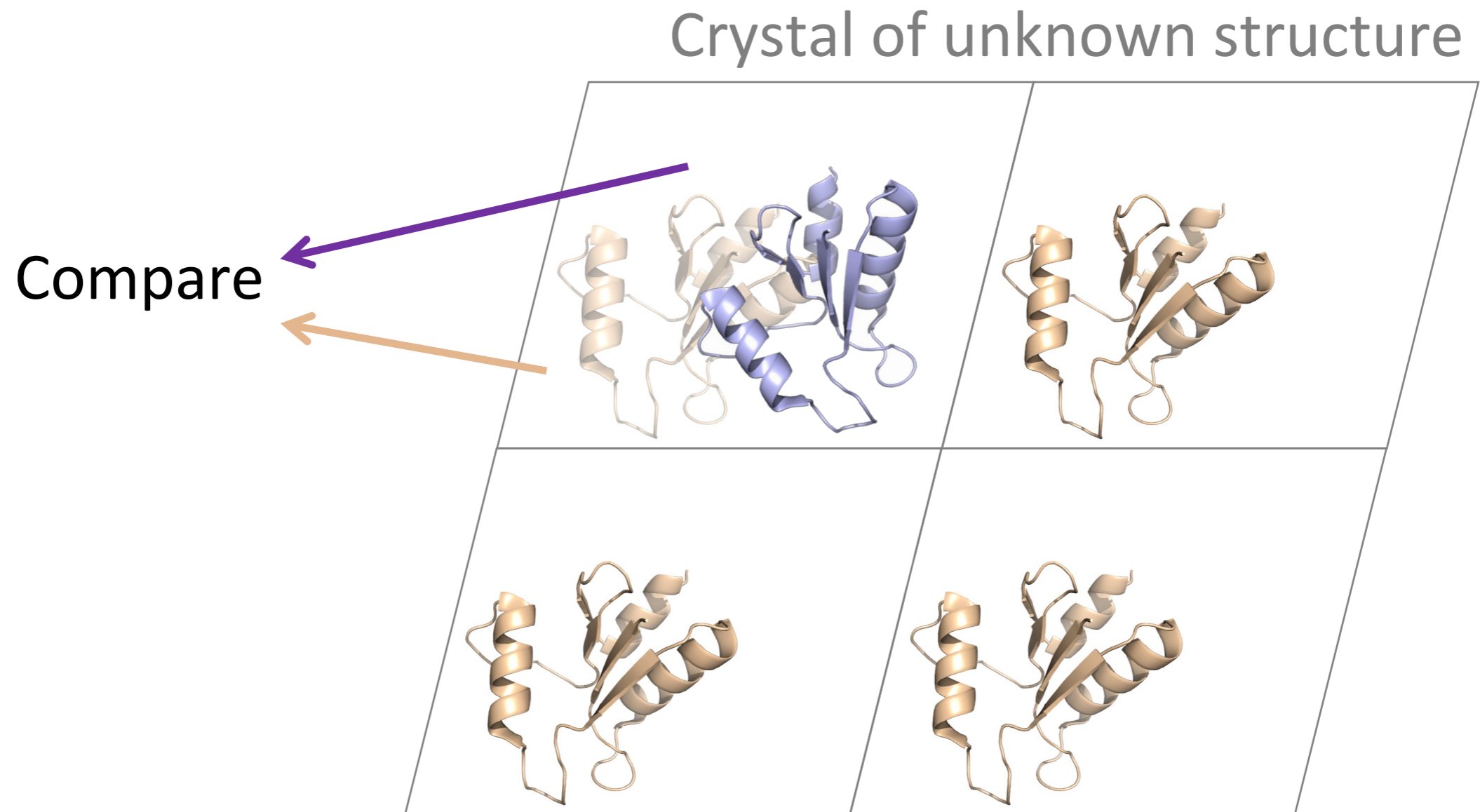
Molecular replacement: Approach



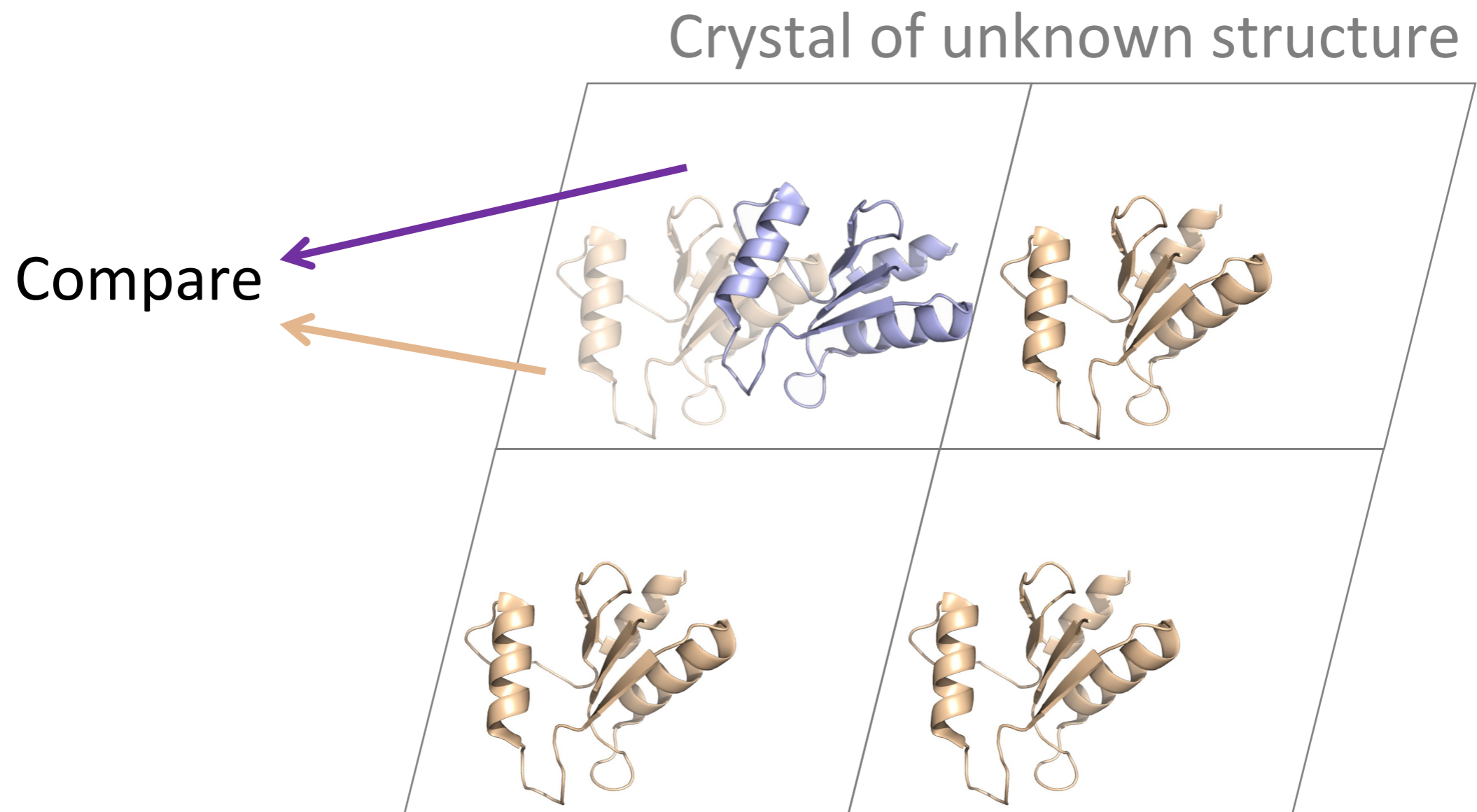
Molecular replacement: Approach



Molecular replacement: Approach



Molecular replacement: Approach




Challenges of MR

- 1) How to choose a search model (how to modify it)
- 2) Speed of the calculations
- 3) How to score each orientation and translation (how to differentiate signal from noise?)
- 4) How to do the rotations/translations

[Evans, P.; McCoy, A. An Introduction to Molecular Replacement. *Acta Cryst. D* **2008**, *64* \(1\), 1–10](#)

[Dodson, E. Introduction to Molecular Replacement: A Time Perspective. *Acta Crystallogr D Struct Biol* **2021**, *77* \(7\), 867–879](#)

[McCoy, A. J.; Sammito, M. D.; Read, R. J. Implications of AlphaFold2 for Crystallographic Phasing by Molecular Replacement. *Acta Cryst D* **2022**, *78* \(1\), 1–13](#)

11  Phenix Workshop 11/17/2020 (Xtallography) - Top tips for molecular replacement
Phenix Tutorials

1) The search model

- Critical step in MR.
- Should provide a high proportion of the scattering from the target structure with high accuracy (low r.m.s.d.)
- Homologue structures
 - Low r.m.s.d. → high sequence identity (sequence comparison search)
 - Prune regions of large sequence diversity
 - Truncate side-chains
- Predicted structures (Remove low pLDDT regions, split into domains)

2) Computational tricks to improve the speed

An exhaustive search is very slow even on modern computers.

Each molecule needs six parameters to define its orientation and position.

Example:

3 angles ($0-360^\circ$, $0-180^\circ$, $0-360^\circ$) at 2.5° intervals $\rightarrow 1.5 \times 10^6$ grid points

3 translations in a $100 \times 100 \times 100$ Å cell at 1 Å intervals $\rightarrow 10^6$ grid points

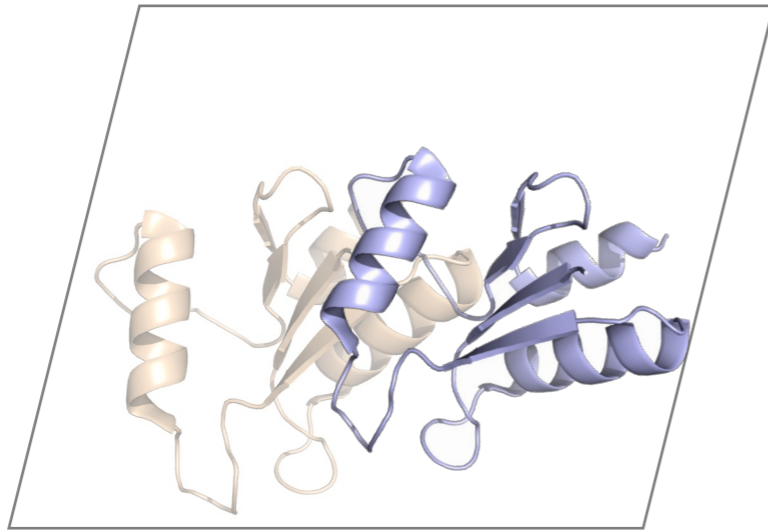
Total search of 1.5×10^{12} points

\rightarrow Separate the two searches: Do rotation first, then the translation

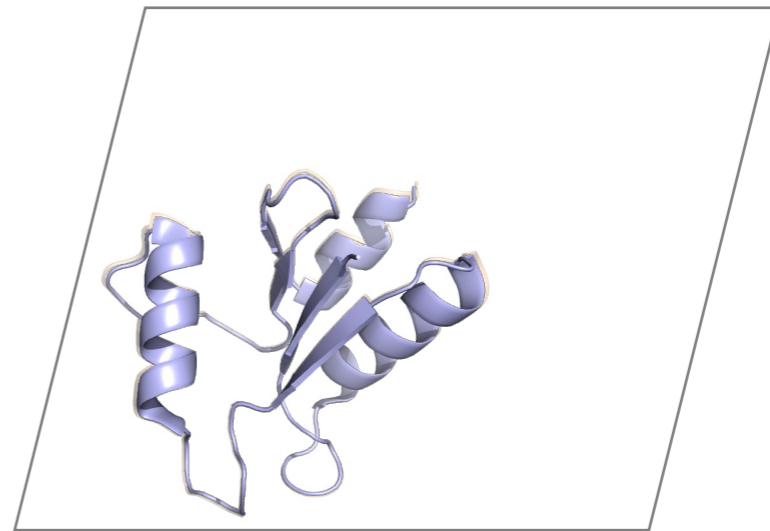
2.5×10^6 points per rotation solution

3) The scoring function

Compare **observed** and **calculated** diffraction.



Poor score



Good score

Different approaches:

- Patterson function (vector map)
- Maximum-likelihood Methods (“for any postulated orientation and position of the model, what is the probability of obtaining the structure amplitudes that we observe?”)

3) The scoring function: ML Method

Explicitly models errors (experimental σ_F and r.m.s. coordinate error of the model)

→ Likelihood methods are more robust and generally give clearer solutions in difficult cases

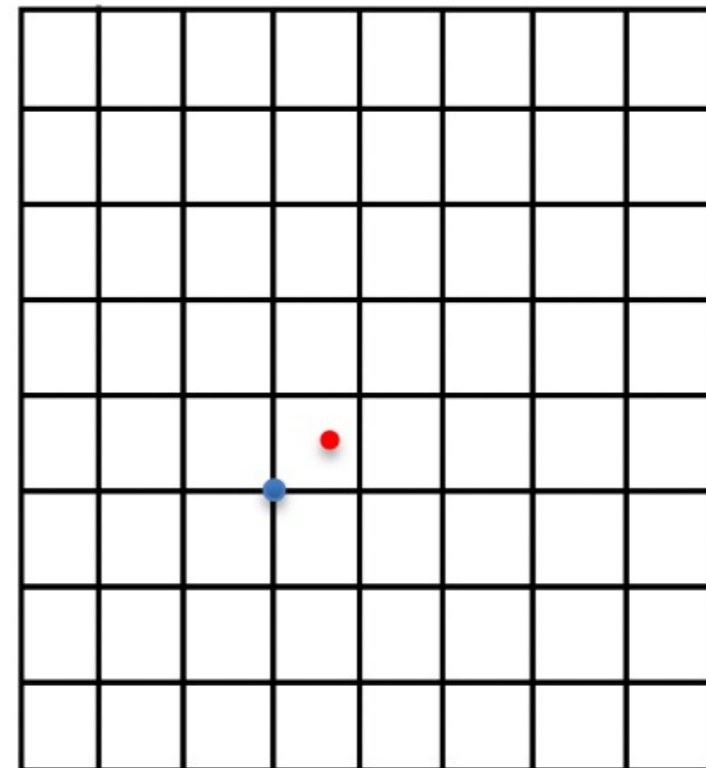
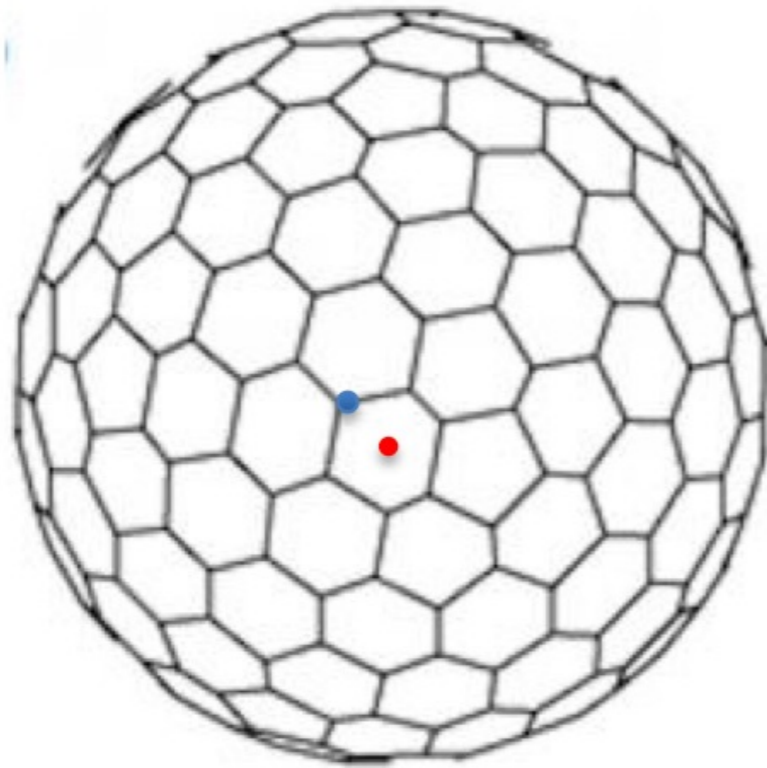
3) The scoring function: ML Method

- Place model at orientations and calculate probability of each being correct
- Place model at points and calculate probability of each being correct
- The scoring function is the LLG
- Do packing analysis to see if there are clashes

3) The scoring function: ML Method

Optimize orientation and position away from grid search Locations.

The scoring function is the LLG



3) The scoring function: ML Method

LLG = Log Likelihood gain

Difference between the likelihood of the model and the likelihood calculated from a Wilson distribution.

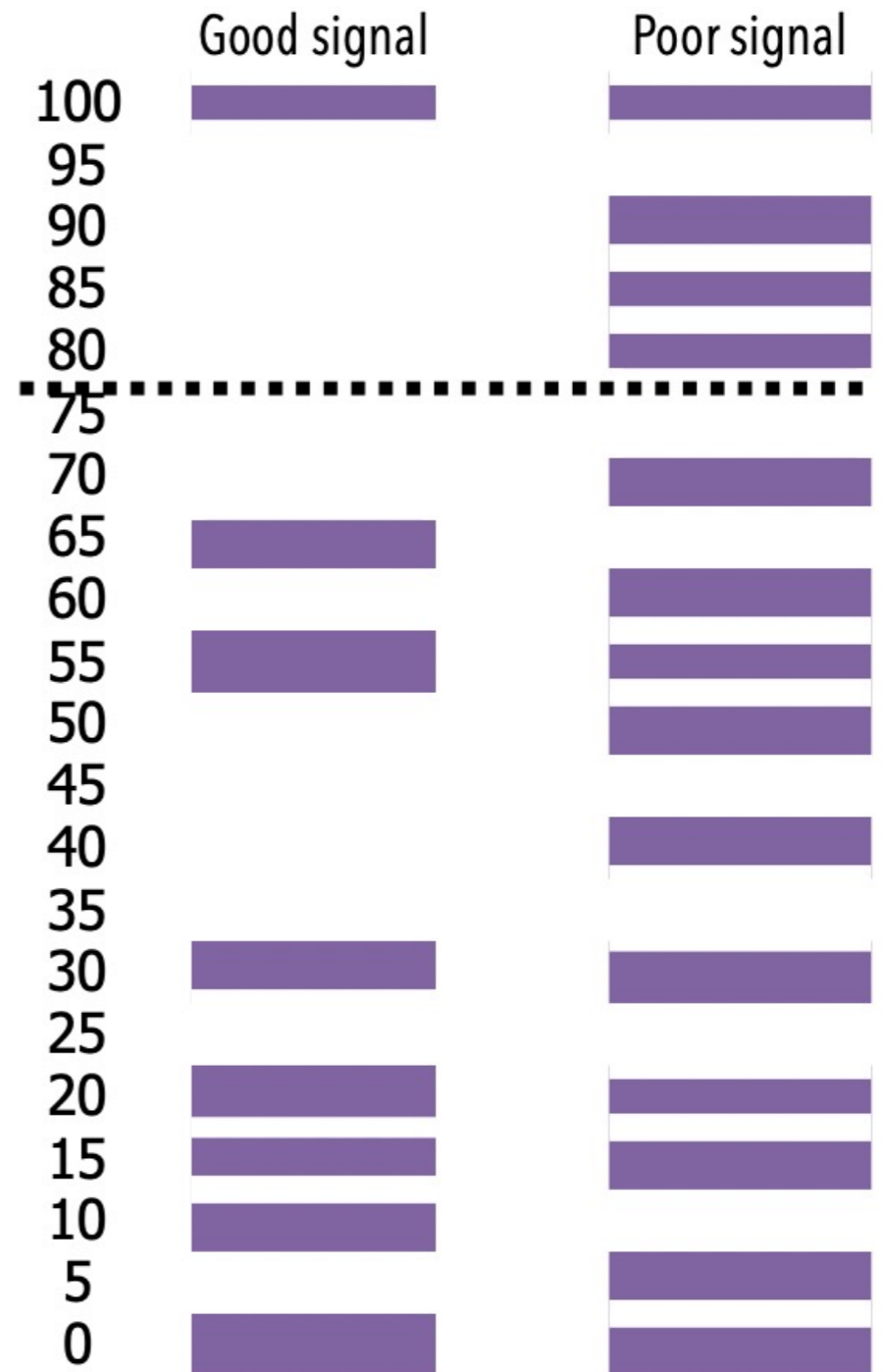
→ it measures how much better the data can be predicted with the search model than with a random distribution of the same atoms.

TF-Z = how many standard deviations your solution is above the mean (the higher the better).

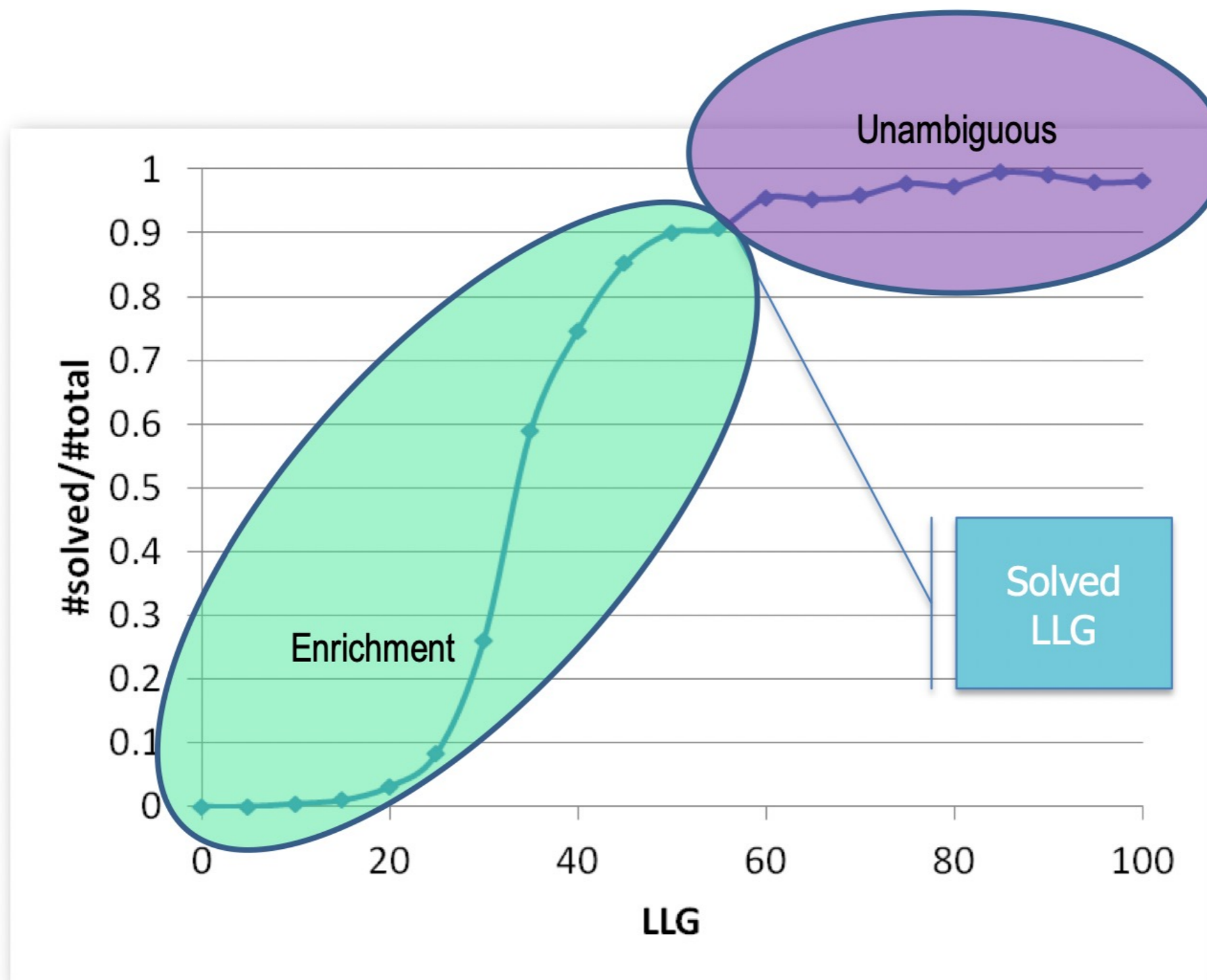
3) The scoring function: ML Method

Solutions over 75% of the difference between the top peak and the mean are selected

- Good signal, few potential solutions
- Poor signal, many potential solutions



3) The scoring function: ML Method



Database of
over 23000
MR problems

Plot of LLG versus success in structure solution

R.D. Oeffner

3) The scoring function: ML Method

TF Z-score	LLG score	Solved?
< 5	< 25	no
5 - 6	25 - 36	unlikely
6 - 7	36 - 49	possibly
7 - 8	49 - 64	probably
> 8	> 64	definitely

4) Search strategies

Need to describe rotations and translations which move the coordinates into a new frame

- Translations
- Rotations (Rotation matrix is inconvenient)
- Different angle conventions
 - Polar angles
 - Eulerian angles
 - Lattman angles

Summary

- Choose and prepare your search model carefully (even predicted models!)
- Know how many molecules/domains you need to place
- MR is successful if $LLG > 64$, $TF-Z > 8$